

# Emulator-based Neural Network Prediction for SIF Retrieval in the O<sub>2</sub>-A Absorption Band

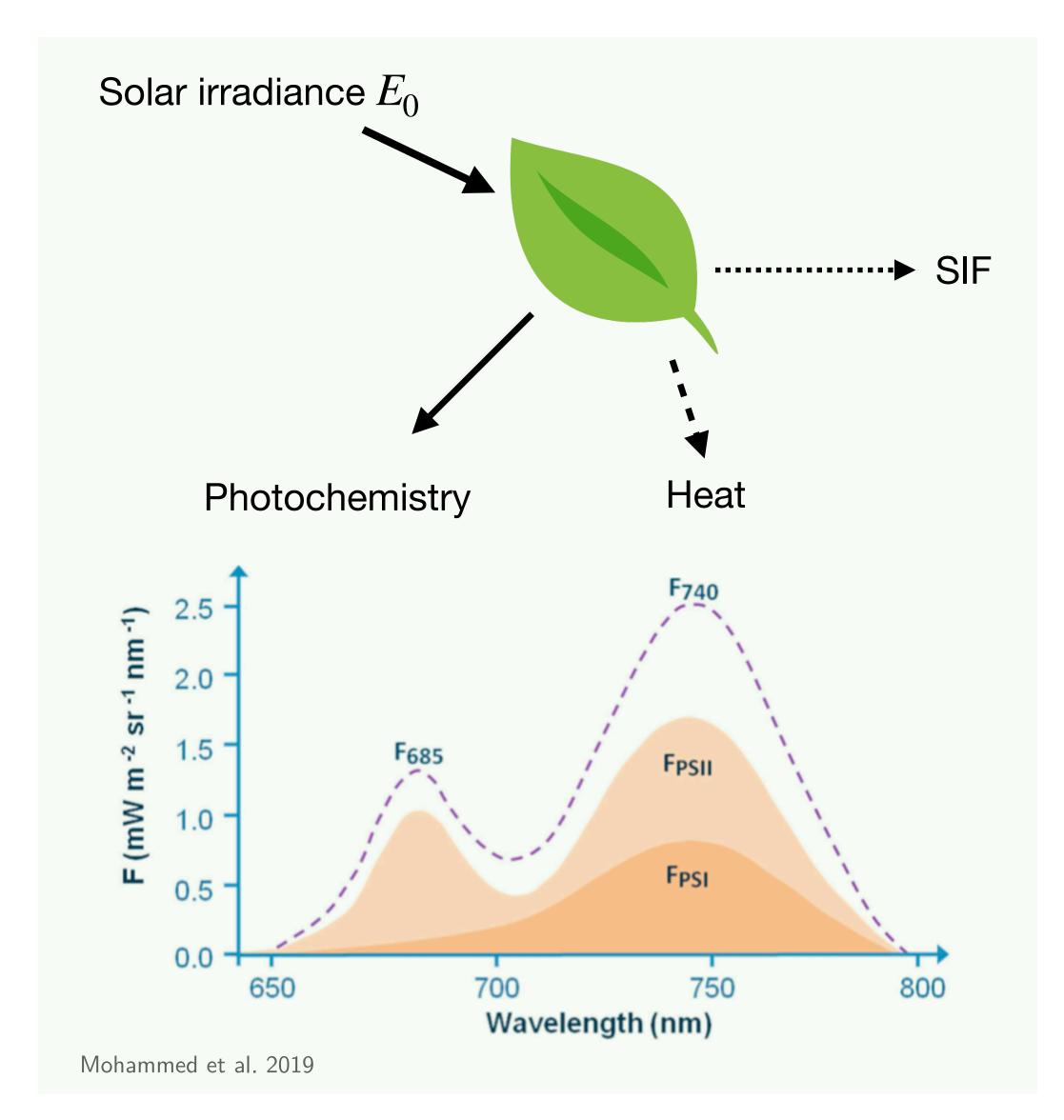
12.06.2023

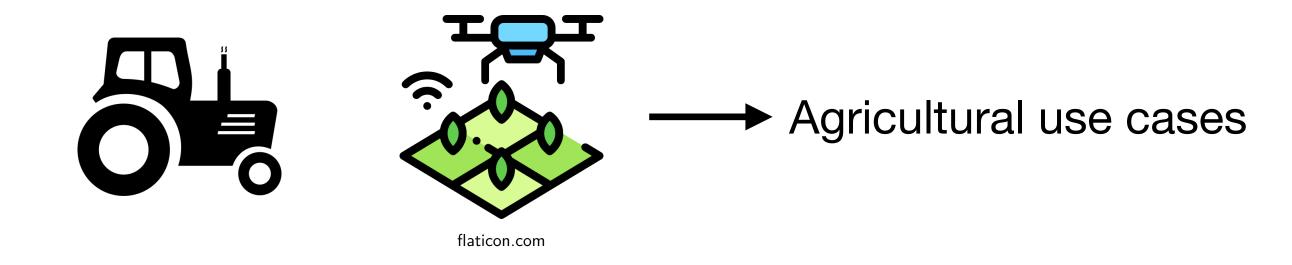
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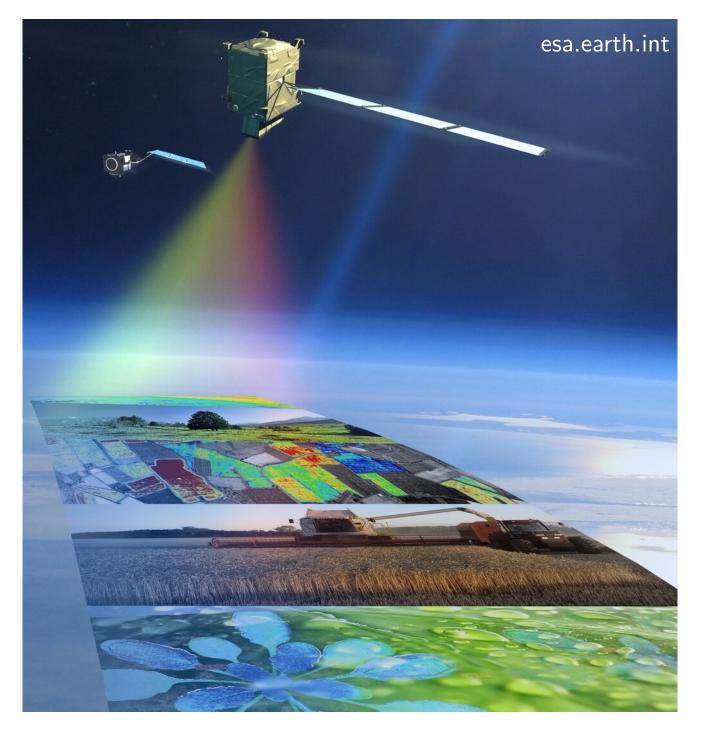
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#### What is Sun-Induced Fluorescence (SIF)?





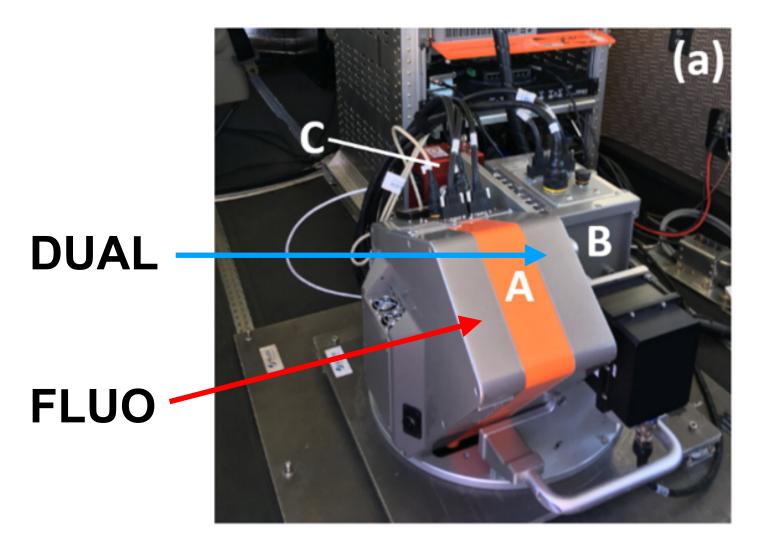


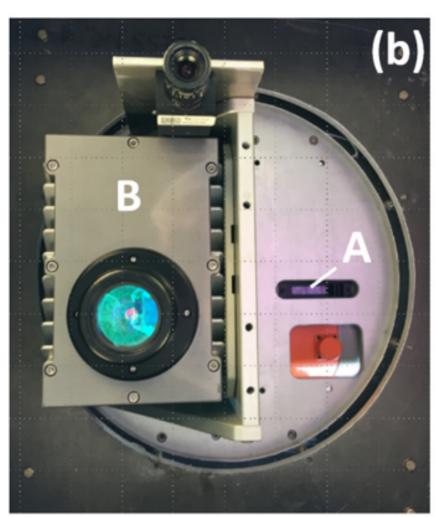
→ ESA Earth Explorer FLEX Global Fluorescence estimations



#### Airborne HyPlant Spectrometer

- FLUO is the airborne demonstrator for FLEX
- 0.24 nm FWHM, 0.11 nm SSI
- 5 years of comparable campaign acquisitions
- 773 acquisitions, 384 × [2000, 10'000] px
- Operational Baseline SIF Retrieval Methods
  - Spectral Fitting Method (SFM),
     Cogliati et al. 2019
  - Improved Fraunhofer Line
     Discrimination (iFLD), Damm et al. 2022



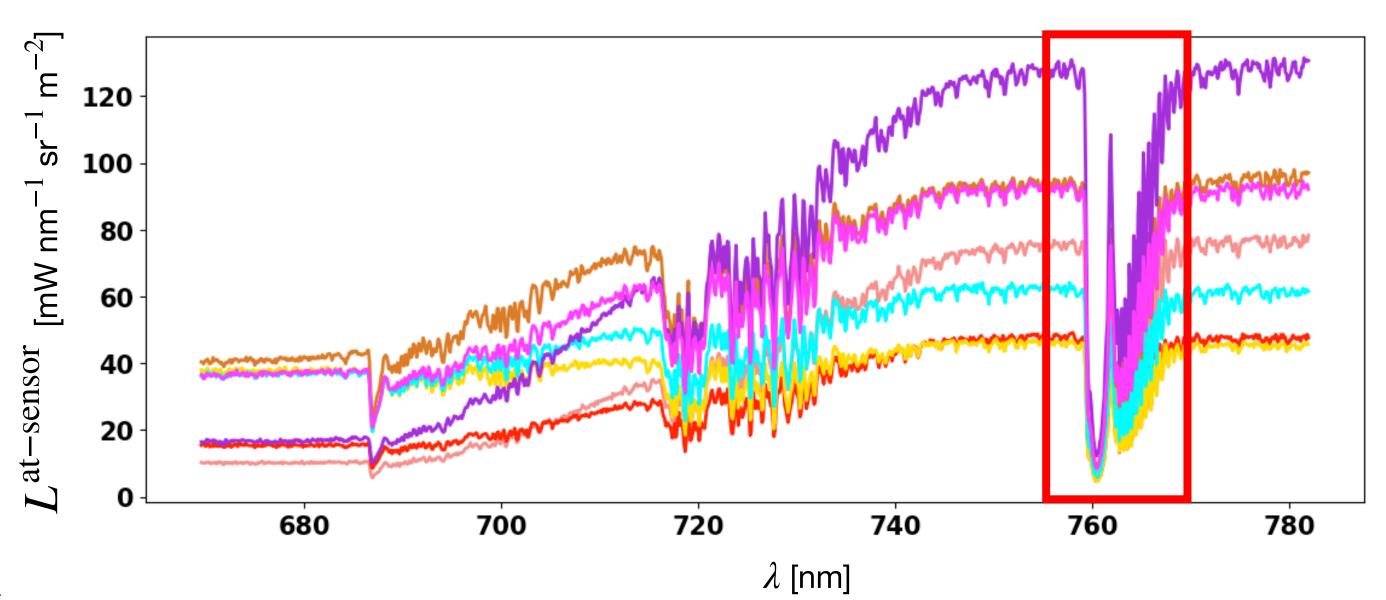




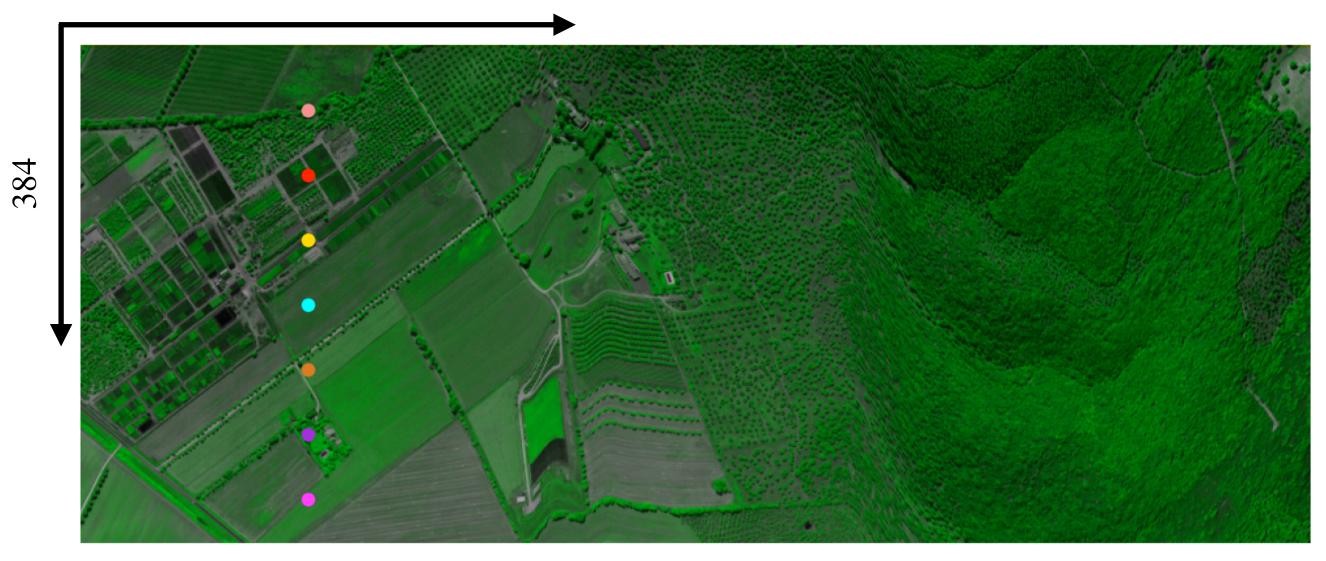
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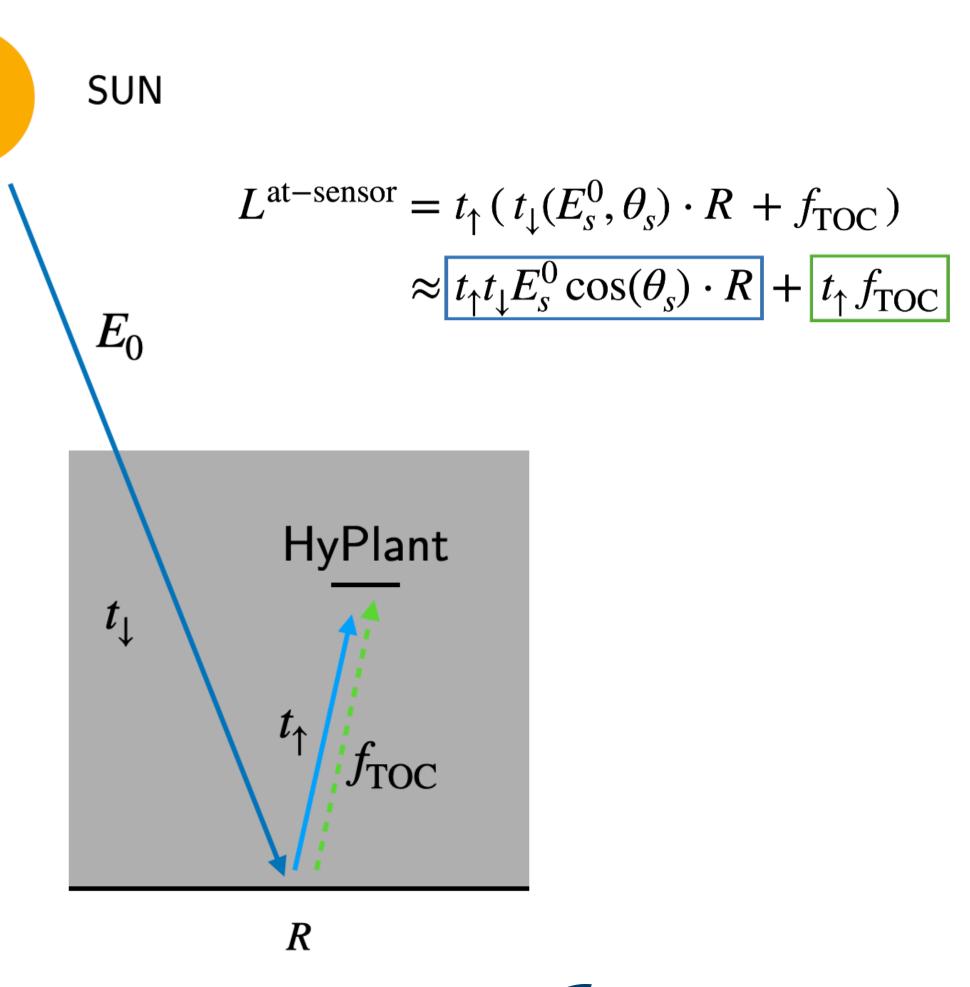


Flight direction  $[2 \times 10^3, 10^4]$ 



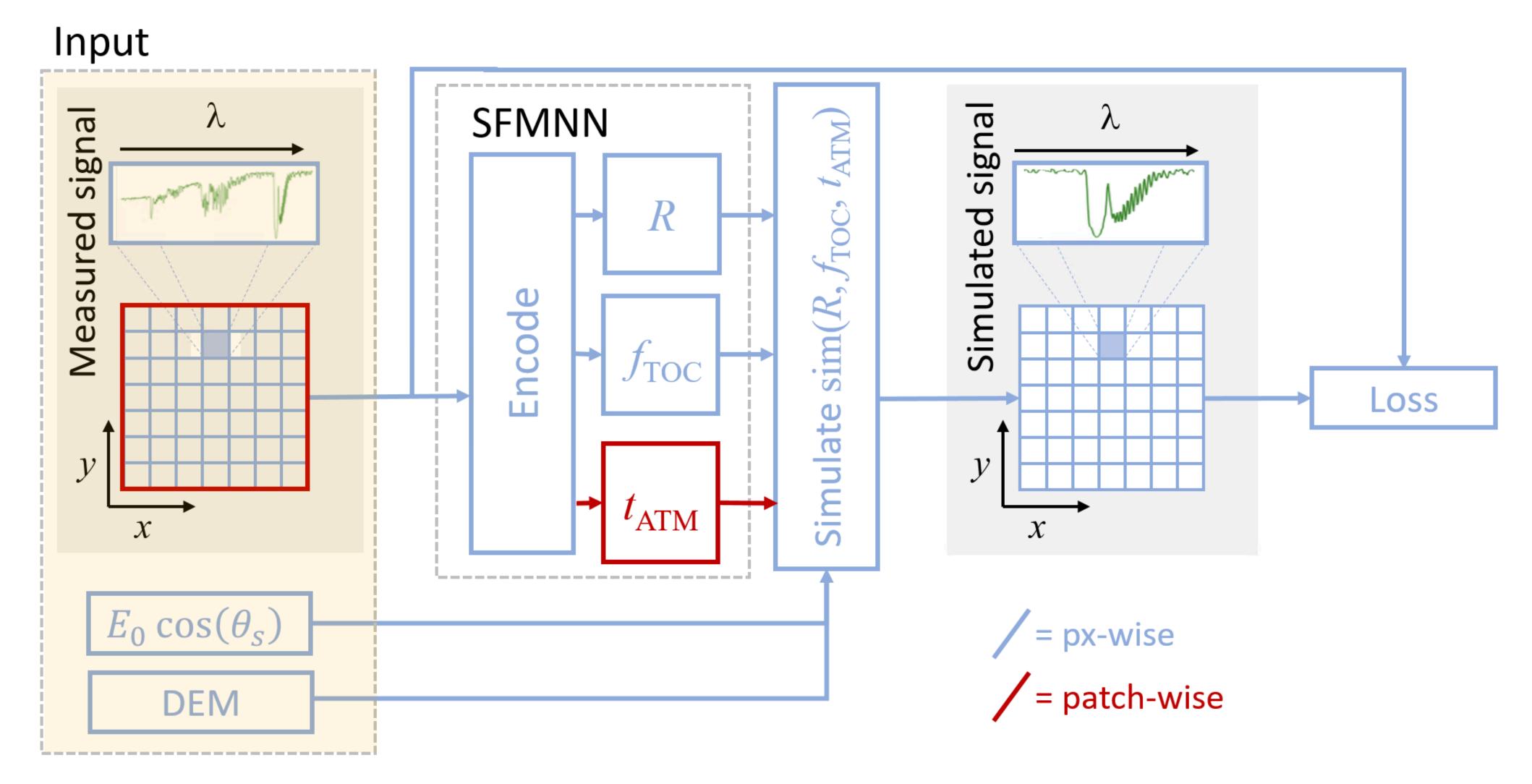
#### Spectral Fitting Methods to Retrieve Fluorescence

- Conventional Least Squares Optimization in Spectral Fitting Method (SFM)
  - Data inefficiency:
     no benefits from statistical relationships
  - Slow:
     Individual fit of each spectral pixel
  - *Model failure:* in topographically variable terrain



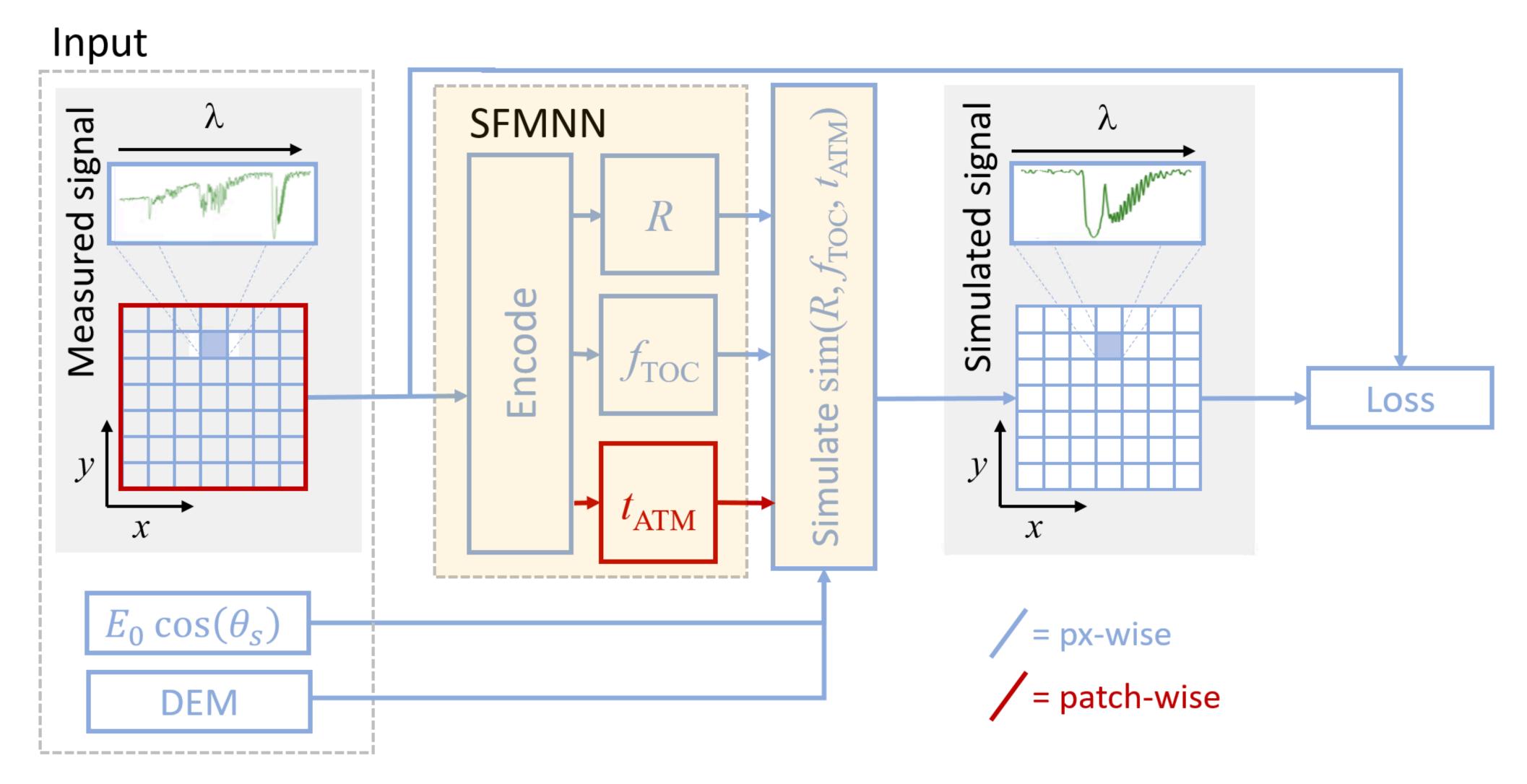


### Spectral Fitting Method Neural Network (SFMNN)





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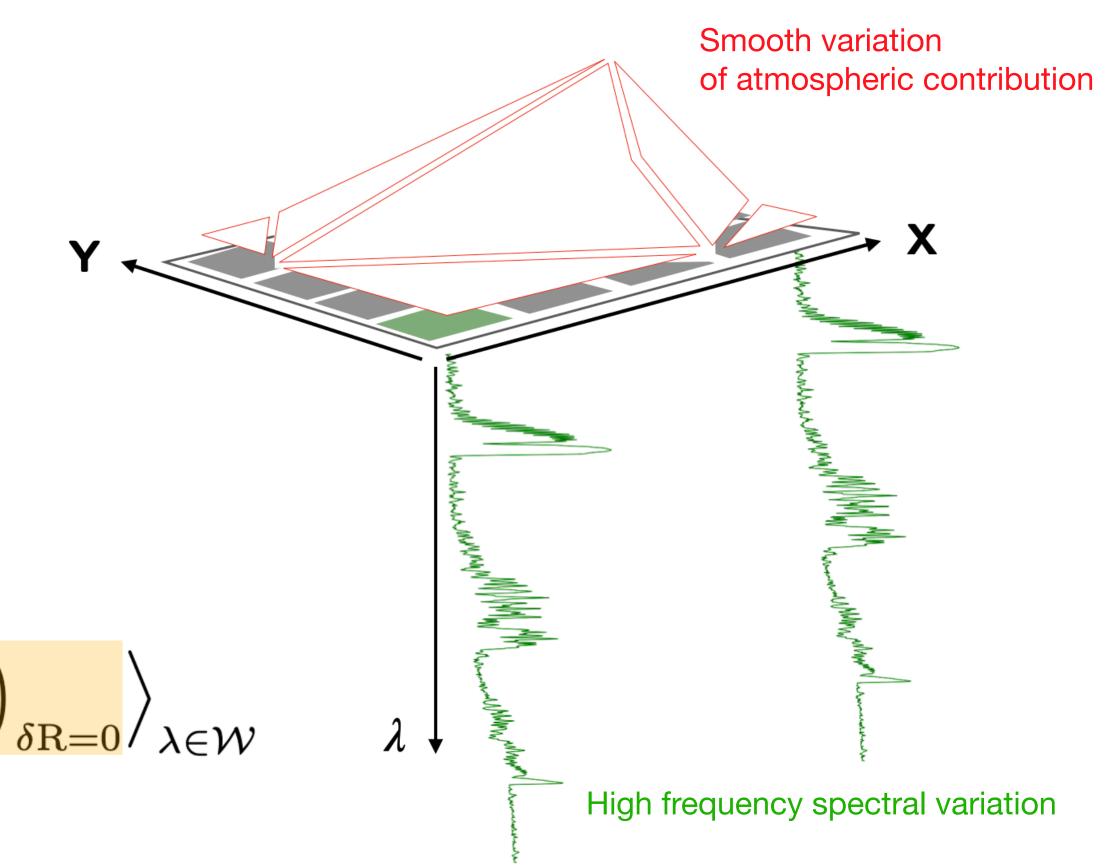
## **Loss and Constraint Formulation** Self-Supervised Loss Formulation for Signal Reconstruction

- Inversion under incomplete knowledge of physical process is ill-posed.
- Architectural constraint formulation: difference in spatial variation of terms contributing to radiance signal

$$\ell(y, \hat{y}) = (\ell_{R,f} + \gamma_f \ell_f + \gamma_N \ell_{NDVI})(y, \hat{y})$$

$$= \left\langle (y(\lambda) - \hat{y}(\lambda))^2 + \gamma_f \left( w_\lambda (y(\lambda) - \hat{y}(\lambda))^2 \right)_{\delta R = 0} \right\rangle_{\lambda \in \mathcal{W}}$$

$$+ \gamma_N \hat{f} \delta (NDVI_y \le t)$$





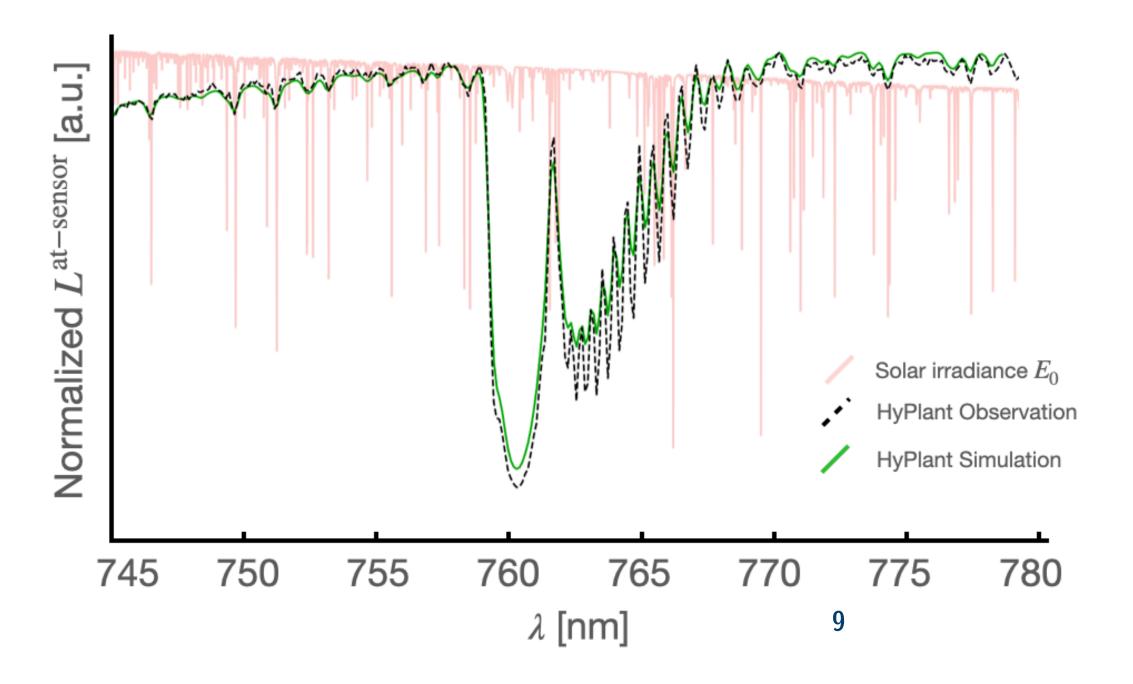


Physiological constraint



#### Simulation of HyPlant At-sensor Radiance

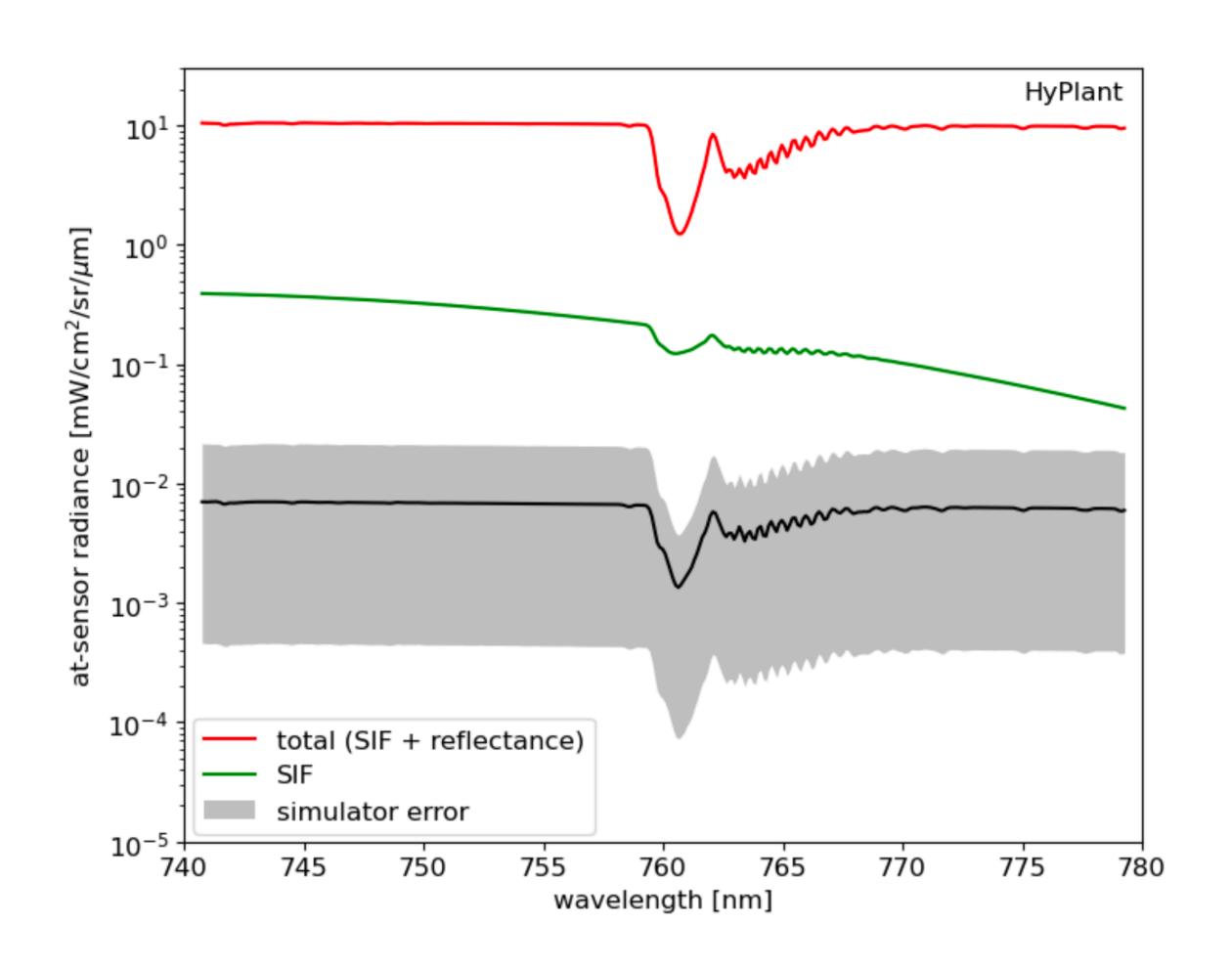
- Radiative Transfer Modelling (MODTRAN)
- Extensive coverage of observational conditions
- Inclusion of topographic variation



	Parameter		HyPlant DB	
13 paramete	Atmosphere	model	mid-latitude summer	
		$H_2O$ [cm]	0.3 – 3.0	
		$O_3$ [DU]	332	
		$\mathrm{AOT}_{550}~[]$	0.05 – 0.40	
	rs	aerosol model	rural	
		g []	[-1, +1]	
	Geometry	TA [°]	0-20	
		SZA [°]	20-55	
		RAA [°]	0-180	
		$h_{ m gnd} \ [ m m]$	0-300	
		$h_{ m sen} \ [{ m km}]$	0.659-0.691  agl	
			1.543-1.598  agl	
	Surface	$ ho_{740} \; []$	0.05 – 0.60	
		$\mathrm{d}  ho/\mathrm{d} \lambda \; [\mathrm{nm}^{-1}]$	0-0.008	
		$F_{737}/F_0$	0–8	
	Sensor	$\delta_{\lambda} \; [{ m nm}]$	[-0.080, +0.023]	
		$\delta_{ m FWHM} \; [ m nm]$	[-0.040, +0.040]	

#### **Emulation of HyPlant At-sensor Radiance**

- High-dimensional regression problem (13 → 349 dims)
- A set of regression models were tested
- Polynomial of 4<sup>th</sup> degree (P4) is precise enough
- P4 was used as forward simulator in SFMNN





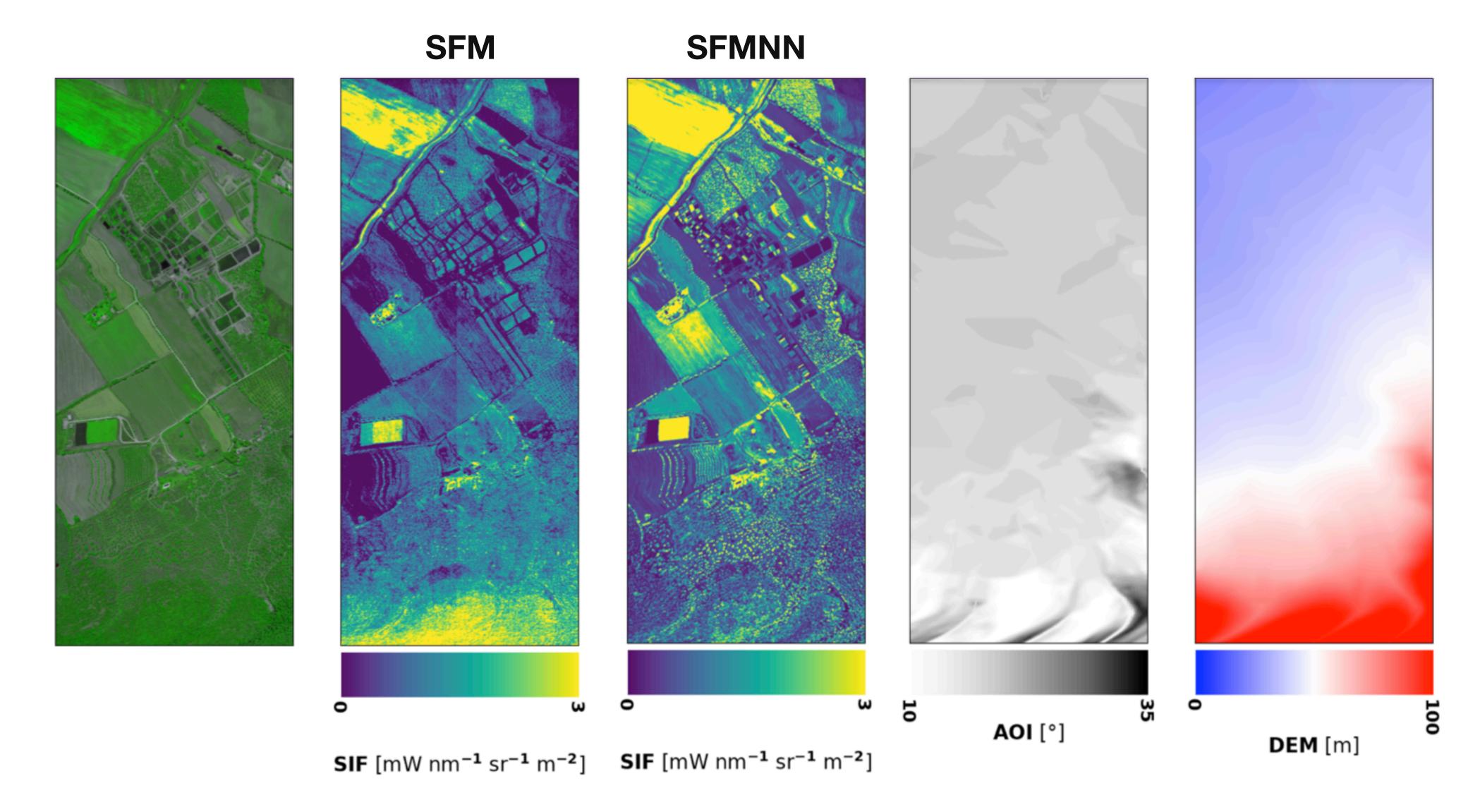
#### Comparison with in-situ measurements

- Small set of synchronous SIF ground measurements
- Good correlation
- Absolute errors impacted by systematic biases
- Might be caused by domain gap between simulations and HyPlant observations

Data Set			MAE	MAE[calib]	
	$r^{ m pear}$		${ m mW~nm^{-1}~m^{-2}~sr^{-1}}$		N
CKA-2020 (600m)	SFM SFMNN iFLD	0.85 0.78 0.53	$egin{array}{c} {f 0.43} \pm {f 0.05} \ 0.90 \pm 0.03 \ 0.41 \pm 0.07 \ \end{array}$	$0.17 \pm 0.02$ $0.18 \pm 0.04$ $0.24 \pm 0.01$	18 18 18
SEL-2018 (600m)	SFM SFMNN iFLD	0.91 <b>0.93</b> 0.82	$0.53 \pm 0.07$ $0.40 \pm 0.03$ $0.61 \pm 0.09$	$0.11 \pm 0.00$ $0.11 \pm 0.00$ $0.18 \pm 0.00$	12 12 12

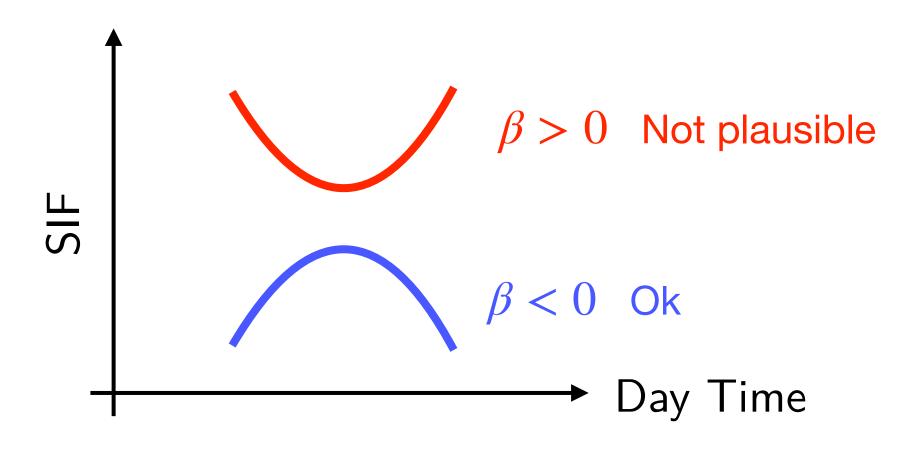


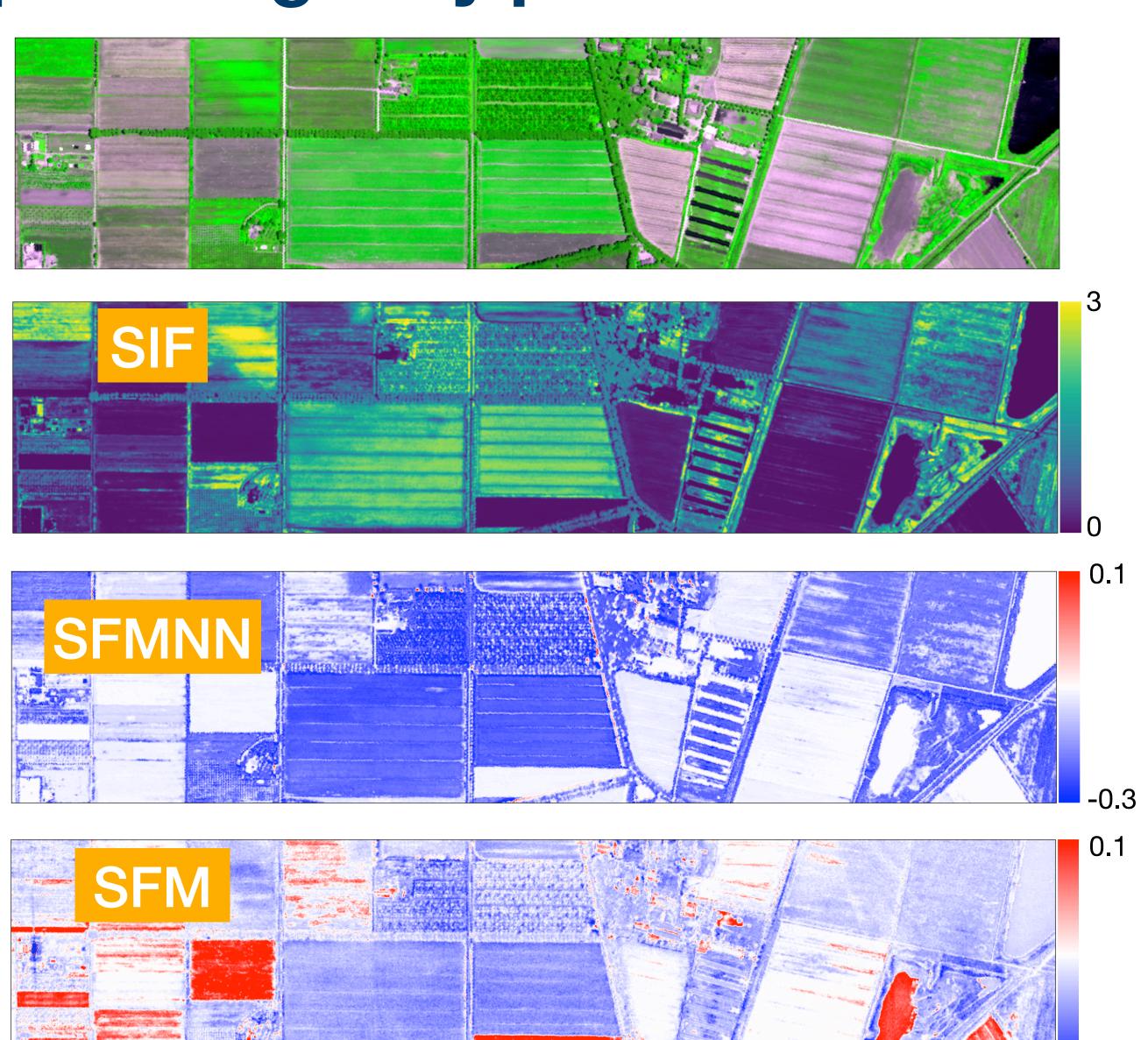
#### SIF Prediction in Topographically Variable Terrain



#### Diurnal SIF Dynamics are phenologically plausible

- Time series from repeated flights
- Second order derivative  $\beta$  as a measure for diurnal SIF dynamics





SIF [mW nm

12.06.23

#### Conclusions & Outlook

- The emulator-based neural network prediction achieves correlation comparable to SFM on a data set of in-situ measurements.
- Further analysis is needed to establish the reasons for systematic errors in absolute SIF prediction.
- The impact of the topographic variation on the atmospheric transfer is compensated in SFMNN.
- SFMNN predicted diurnal SIF dynamics are physiologically plausible.
- The possibility to extend this method to other sensors is currently being evaluated:
  - DESIS (onboard the ISS) in FluoMap
  - FLEX, simulated hyperspectral imagery

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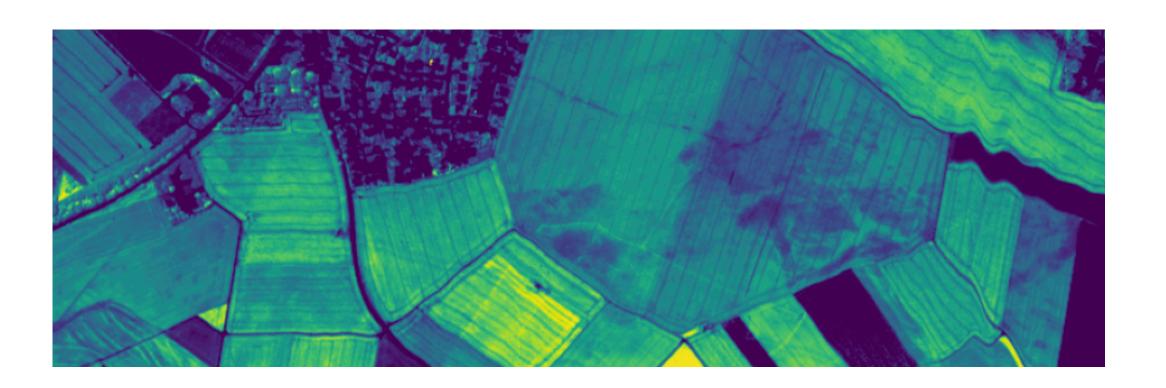
[1] Jülich Supercomputing Centre. (2021). JURECA: Data Centric and Booster Modules implementing the Modular Supercomputing Architecture at Jülich Supercomputing Centre Journal of large-scale research facilities, 7, A182. http://dx.doi.org/10.17815/jlsrf-7-182

#### FluoMap Project Members

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Mitglied der Helmholtz-Gemeinschaft

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