

# Fire Simulation with adaptive FEM

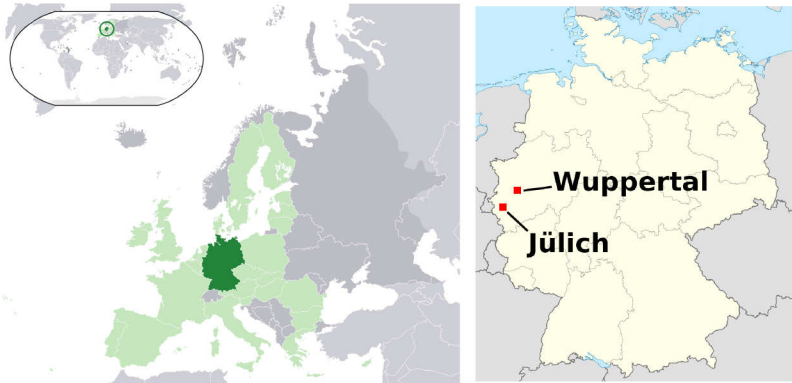
April 3, 2018 | Marc Fehling | Civil Safety Research (CSR)

# Introduction

- Marc Fehling
- M. Sc. Physics, Ruhr-University Bochum, Germany, 2015
- since November 2015:  
PhD candidate at  
Jülich Research Centre (FZJ),  
institute Civil Safety Research (CSR),  
associated with the University of  
Wuppertal (BUW)



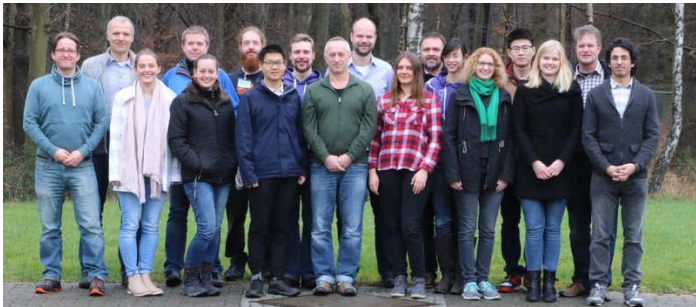
## Introduction: Location



**Figure:** Locations of the Jülich Research Centre and the University of Wuppertal. (source: wikipedia)

# Introduction: Civil Safety Research

- Concerns: Pedestrian behavior and safety
  - i.e. in emergency situations (e.g. caused by fires)
- Scientists from various fields
  - mathematicians, physicists, engineers, programmers, etc.



**Figure:** Members of the institute Civil Safety Research.

# Introduction: Supercomputers

- Jülich Supercomputing Centre (JSC) houses supercomputers
  - General purpose cluster JURECA
  - High scaling cluster JUQUEEN
    - Shutdown in March 2018. Replaced by successor JUWELS.



**Figure:** Supercomputers at Research Centre Jülich. (source: JSC)

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## Motivation: Fire Safety

- Safety measures increase chance of survival of inhabitants in case of emergency.
- Fire safety measures:
  - Fire doors, building materials, smoke extraction, sprinklers, ...
- German legislation prescribes 'building codes'.
  - For 'normal' purposes:
    - residential buildings
  - For 'special' purposes:
    - event halls
    - malls
    - garages
    - factories
    - skyscrapers
    - airports / train stations
    - ...

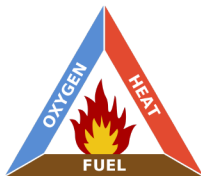


Figure: Fire triangle. (source: wiki)

## Motivation: Architecture

- Modern architecture and large-scale projects may not fit in 'building code'
- Individual considerations necessary:
  - Model experiments, CFD investigations, ...



**Figure:** Interior of BMW World, Munich. (source: mazdaspeed.pl)

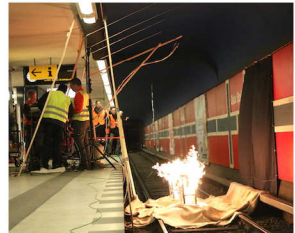
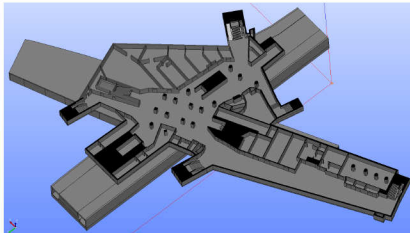


## Motivation: Project Orpheus



Optimierung der **R**auchableitung und **P**ersonenführung in  
U-Bahn**h**öfen: **E**xperimente und **S**imulationen

- Smoke and fire spread in complex metro stations
  - High dimensional parameter space for fire scenarios, including underground climate



## Motivation: Project Orpheus II

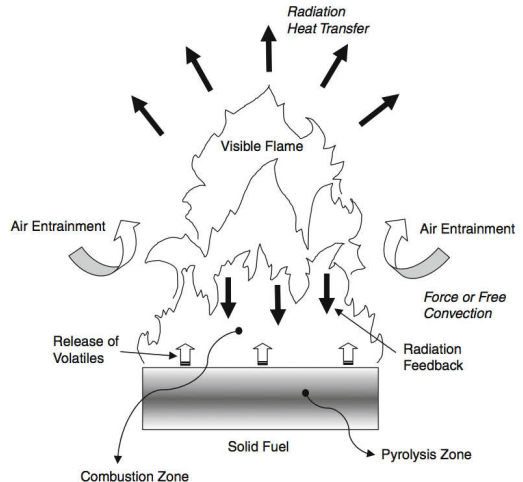


**Figure:** Video of experiments in the metro station.

# Modeling: Fires

Processes to consider:

- Fluid dynamics
  - Navier–Stokes equations
  - Turbulence
- Combustion
- Radiation
- Conduction
- Pyrolysis



**Figure:** Burning solid fuel in air with physical processes involved. [1]

## Modeling: Buoyancy driven flows

- Consider low Mach number limit (  $Ma = u/c_{\text{sound}} \rightarrow 0$  )
- Propagation of fluids with incompressible Navier–Stokes (INS) equations:

$$\nabla \cdot \mathbf{u} = 0$$

$$\rho_0 [\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u}] + \nabla p - \nabla (2\mu \epsilon_{ij}(\mathbf{u})) = \mathbf{f}(T)$$

$$\rho_0 c_p [\partial_t T + (\mathbf{u} \cdot \nabla) T] - \nabla \cdot (\kappa \nabla T) = g(\mathbf{u})$$

with strain rate tensor  $\epsilon_{ij}(\mathbf{u}) = \frac{1}{2} [\nabla_i u_j + (\nabla_j u_i)^T]$ .

- Prandtl number connects viscous to thermal diffusion:

$$Pr = \frac{\nu}{\alpha} = \frac{c_p \mu}{\kappa}$$

with  $c_p = \frac{5}{2} \frac{R}{M}$  specific heat for monoatomic ideal gases

## Modeling: Turbulence

- Avoid resolving the dissipative scales by modeling turbulence
  - Kolmogorov length of air  $\sim 25 \mu\text{m}$
- Apply filtering to model effect of small eddies
  - time filtering: Reynolds-Averaged-Navier-Stokes (RANS)
    - separation of observables in mean and fluctuations
    - averages over fluctuations
    - justification: transport processes happen on large time scale
  - space filtering: Large Eddy Simulation (LES)
    - averaging over filter width  $\Delta$  on subgrid scales (SGS)
    - result: effect of small dissipating eddies by adjusting viscosity

## Modeling: LES

- Filter width typically related to mesh:  $\Delta = (h_x h_y h_z)^{1/3}$
- Superposition of viscosity:  $\mu = \mu_{mol} + \mu_{turb}$
- Smagorinsky-Lilly model:

$$\mu_{turb} = \rho (C_s \Delta)^2 \left\| \epsilon_{ij}(\mathbf{u}) \right\|_2, \quad C_s = 0.2$$

- Deardorff model:

$$\mu_{turb} = \rho C_V \Delta \frac{1}{\sqrt{2}} \left\| \bar{\mathbf{u}} - \hat{\mathbf{u}} \right\|_2, \quad C_V = 0.1$$

with  $\bar{\mathbf{u}}$  cell-averaged and  $\hat{\mathbf{u}}$  a weighted average, i.e.

$$\hat{u}_{x,jk} = \frac{\bar{u}_{x,jk}}{2} + \frac{\bar{u}_{x,i-1,jk} + \bar{u}_{x,i+1,jk}}{4}$$

# Modeling: Source terms

- Momentum sources: Gravity and buoyancy
- Buoyancy effects modeled with Boussinesq approximation

$$\mathbf{f}(T) = \underbrace{\rho_0 \mathbf{g}}_{\text{gravity}} - \underbrace{\rho_0 \mathbf{g} \beta (T - T_0)}_{\text{buoyancy}}$$

with  $\beta = T_0^{-1}$  thermal expansion coefficient for ideal gases

- Temperature sources: Convective heat and friction

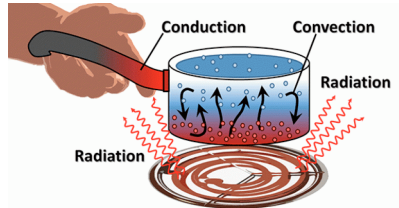
$$g(\mathbf{u}) = \underbrace{\dot{q}_{conv}'''}_{\text{convective heat}} + \underbrace{\nabla (2 \mu \mathbf{u} \cdot \epsilon_{ij}(\mathbf{u}))}_{\text{friction}}$$

# Modeling: Heat transfer

- Heat released by combustion transfers into three different types

$$\dot{q}_{\text{combustion}}''' = \dot{q}_{\text{conduction}}''' + \dot{q}_{\text{convection}}''' + \dot{q}_{\text{radiation}}'''$$

- There is no rule on how generated heat is partitioned
- Needs to be determined empirically / estimated



**Figure:** Types of heat transfer.  
(source: machinedesign.com)



# Modeling: Combustion: Infinitely fast chemistry

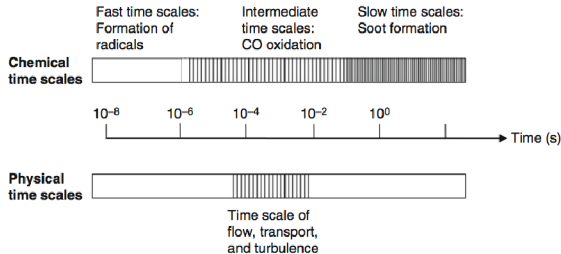


Figure: Chemical and physical time scales. [1]

- Simplification: Infinitely fast reaction of lumped species

$$\dot{q}_{\text{comb}}''' = - \sum_{\alpha} \Delta h_{f,\alpha} \dot{m}_{\alpha}'''$$

with heat of formation  $\Delta h_f$  and mass generation  $\dot{m}'''$

## Modeling: Combustion: Finite rate formulation

- Keep track of each lumped species via mass fractions

$$Y_i = \frac{m_i}{m}, \quad \partial_t(\rho Y_i) + \nabla \cdot (\rho \mathbf{u} Y_i) - \nabla \cdot (\rho D_i \nabla Y_i) = R_i$$

with reaction rate of fuel depending on concentrations

$$R_{fuel} = k(T) C_{fuel} C_{oxy} = k(T) \rho^2 Y_{fuel} Y_{oxy}$$

- Specific reaction rate as Arrhenius expression

$$k(T) = A_0 T^n \exp\left(-\frac{E_a}{k_B T}\right)$$

where  $A_0$ ,  $n$ ,  $E_a$  are empirically determined

## Modeling: Combustion: Conserved scalars

- Mixture of oxygen and fuel gases determine reaction

$$f Y_f + (1 - f) Y_A = Y_M \quad \Rightarrow \quad f = \frac{Y_M - Y_A}{Y_F - Y_A}$$

- With equal diffusivities, transport eqs. can be reduced to

$$\partial_t (\rho f) + \nabla \cdot (\rho \mathbf{u} f) - \nabla \cdot \left( \left( \frac{\mu}{Sc} + \frac{\mu_T}{Sc_T} \right) \nabla f \right) = 0$$

with Schmidt number  $\rho D = \mu Sc$ .

Subscript  $T$  denotes turbulent properties.

- Source terms cancel, thus  $f$  is a conserved scalar



## Modeling: Even more to come...

Model can be arbitrarily complex. What we haven't dealt with

- Pyrolysis – thermochemical decomposition of solid fuel
- Radiation
- Thermal conduction through solid materials
- Flame propagation
- Turbulent combustion
- ...

Literature recommendations:

- NIST FDS documentation. <https://pages.nist.gov/fds-smv>
- Yeoh & Yuen. CFD in Fire Engineering.  
doi:10.1016/B978-0-7506-8589-4.X0001-4

## Numerical methods

We consult numerical methods to solve the model equations

Spatial discretization methods for computational fluid dynamics and software packages using it:

- Finite Difference Method (FDM)
  - [Open source](#): NIST Fire Dynamics Simulator (FDS), ...
- Finite Volume Method (FVM)
  - [Open source](#): FireFOAM (OpenFOAM), ...
- Finite Element Method (FEM)
- Lattice–Boltzmann Method (LBM)

## FEM: Features

Why use FEM?

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- Unstructured grids
  - Allow for better domain representation without aliasing



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- hp-adaptivity
  - Dynamic resolution of numerical grid
  - Adaptive polynomial degree of basis functions
    - Increase accuracy where the action is happening!

## FEM: Features

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- Unstructured grids
  - Allow for better domain representation without aliasing
- hp-adaptivity
  - Dynamic resolution of numerical grid
  - Adaptive polynomial degree of basis functions
    - Increase accuracy where the action is happening!
- Discontinuous Galerkin (DG) methods
  - Allow discontinuities across cell borders
  - Continuous Galerkin (CG) methods unstable for advection like problems, thus require stabilization

## Our implementation

- Motivation of PhD project:
  - Investigate applicability of adaptive methods for fire simulation
  - Use FEM with its unique feature of hp–adaptivity
- Use open–source library `deal.II` [2]
  - 'Toolbox' for the creation of FEM codes



Differential **E**quations **A**nalysis **L**ibrary

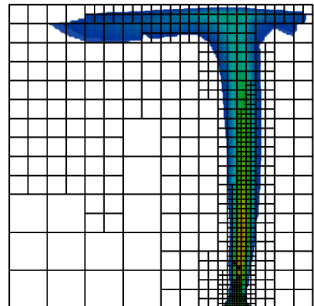
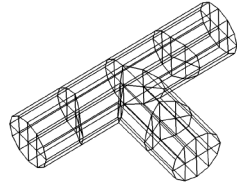
# Our implementation: Features

## Implemented:

- Unstructured grids
- Continuous Galerkin Methods
- Adaptive mesh refinement (AMR)
- MPI parallelization
- Utilization of CAD models as manifolds for mesh refinement

## Current field of activity:

- Verification of flow solver
- Discontinuous Galerkin methods
- p-adaptivity

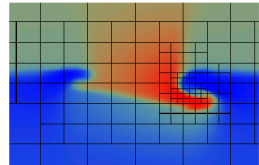
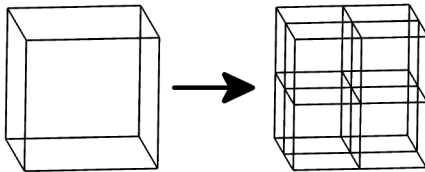


## Adaptive mesh refinement (AMR)

- Solution of differential equations with *FEM* requires:
  - Discretization of space in cells of length  $h$
  - Shape functions with polynomial degree  $p$
- But: The more accurate the solution by choosing  $h$  and  $p$ , the longer the computation

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  - Discretization of space in cells of length  $h$
  - Shape functions with polynomial degree  $p$
- But: The more accurate the solution by choosing  $h$  and  $p$ , the longer the computation
- **Adaptive refinement** as a 'compromise'
  - Adjustment of parameters locally where necessary
  - Variable mesh precision at runtime



J. Dreher, RUB

## AMR: Algorithm

How to determine refinement criteria?

Set up decision criterion for refinement/coarsening

Our choice:

- Calculate  $||\nabla u||$  on each cell
- Normalize values with respect to all cells

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## AMR: Algorithm

### How to determine refinement criteria?

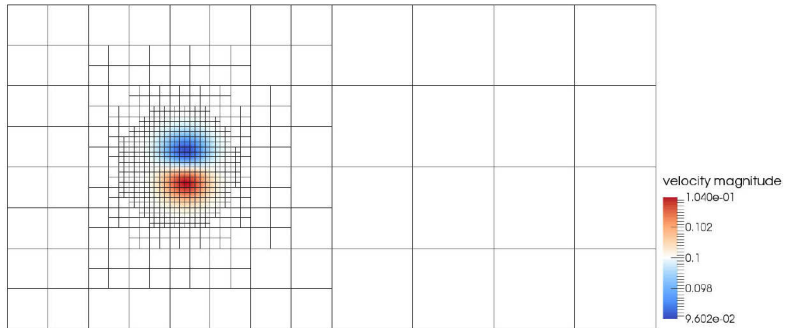
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Our choice:

- Calculate  $||\nabla u||$  on each cell
- Normalize values with respect to all cells
- Flag top/lower 30% for refinement/coarsening at each step
- Define max/min refinement levels as upper/lower bounds
- Neighboring cells are not allowed to differ by more than one level of refinement

## AMR: Verification Example

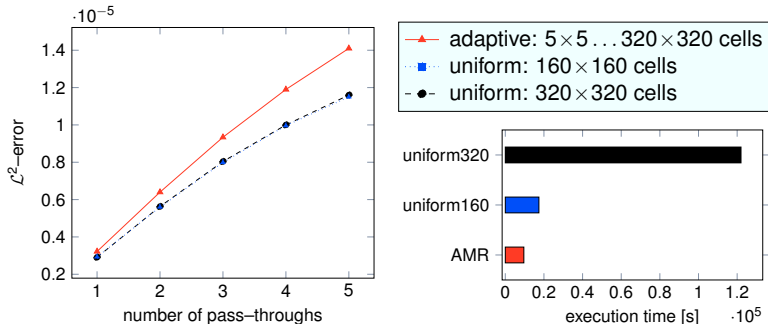
- Demonstration of adaptive mesh refinement via moving vortex test case as a shape-preserving potential stream



**Figure:** Video of velocity magnitude of moving vortex, overlaid with corresponding mesh.

## AMR: Benefits

- Comparison of runtime and accuracy between uniform and adaptively refined meshes with the moving vortex example



**Figure:** Global  $\mathcal{L}^2$ -errors at each periodic pass-through of the vortex.

**Figure:** Execution time of the vortex simulation, run in serial on a common desktop computer.

# AMR: Errors

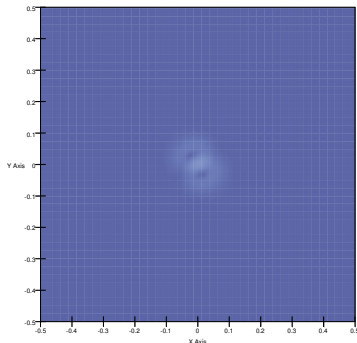


Figure: Static mesh.

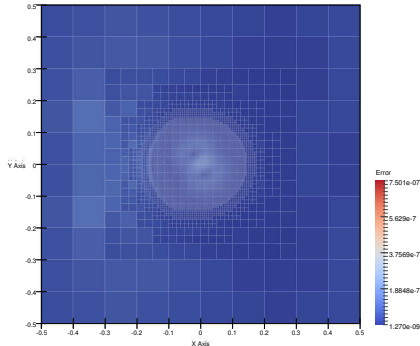


Figure: Adaptive mesh.

1 pass-through.

# AMR: Errors

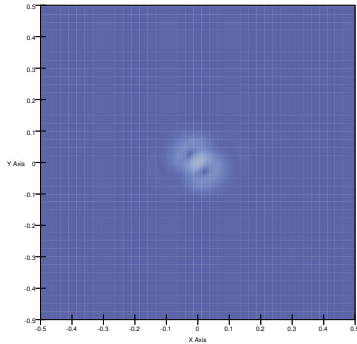


Figure: Static mesh.

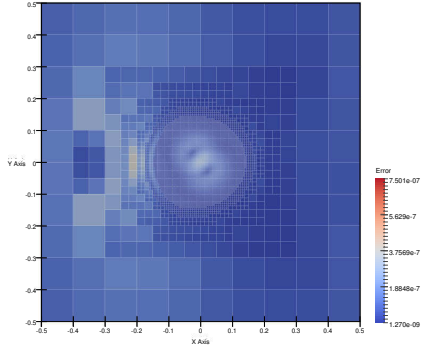


Figure: Adaptive mesh.

2 pass-throughs.

# AMR: Errors

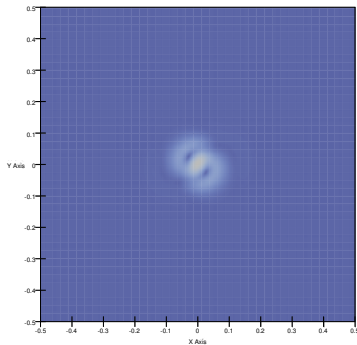


Figure: Static mesh.

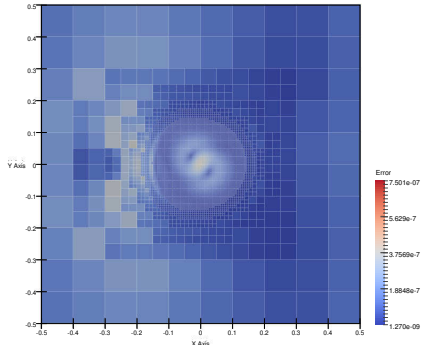


Figure: Adaptive mesh.

3 pass-throughs.

# AMR: Errors

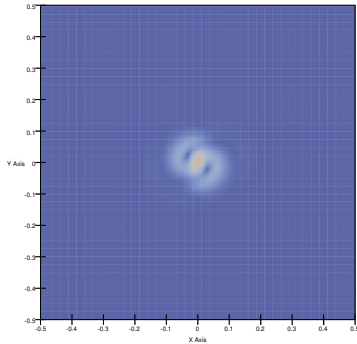


Figure: Static mesh.

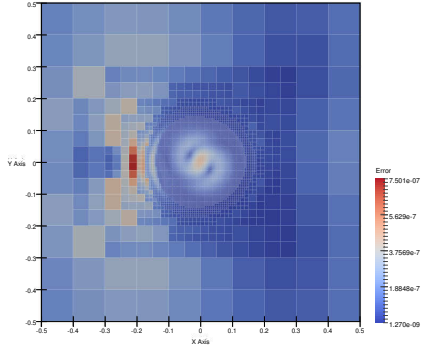


Figure: Adaptive mesh.

4 pass-throughs.

# AMR: Errors

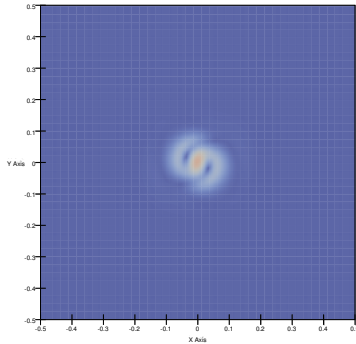


Figure: Static mesh.

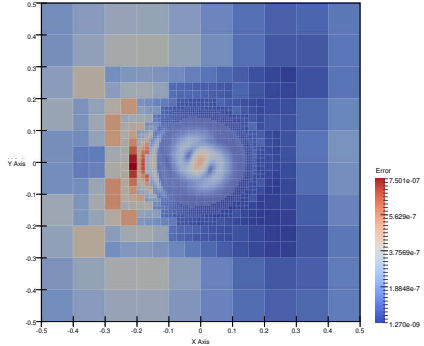
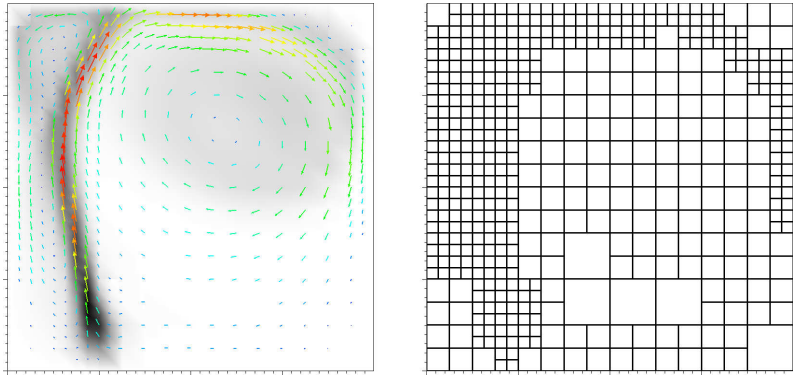


Figure: Adaptive mesh.

5 pass-throughs.



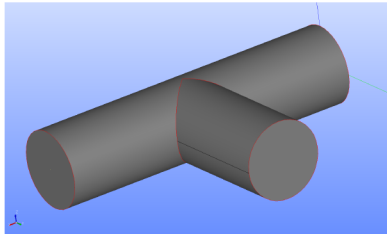
# AMR: Buoyancy example



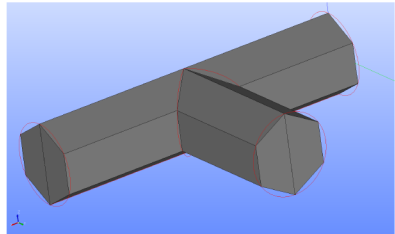
**Figure:** Exemplary simulation of a buoyancy driven flow with a Gaussian heat source.

# Unstructured Grids: Example: T-pipe

- Why T-pipe?
  - Compound bodies
  - Crooked areas (→ cylinder casing area)
  - Discontinuous edges (→ 'welding seam')
- Develop procedure for the creation of appropriate initial meshes

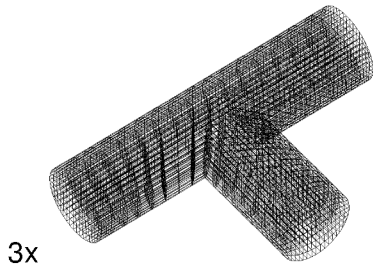
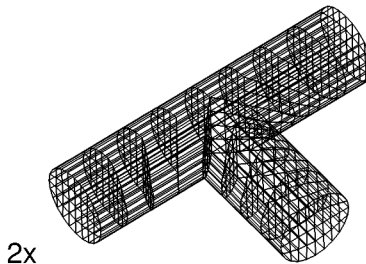
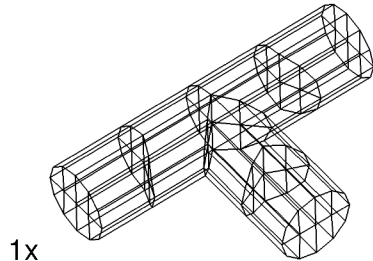
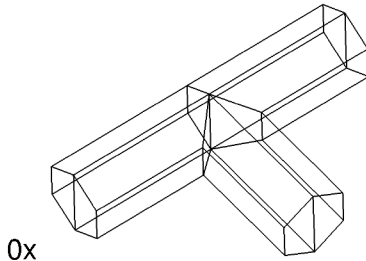


CAD model.



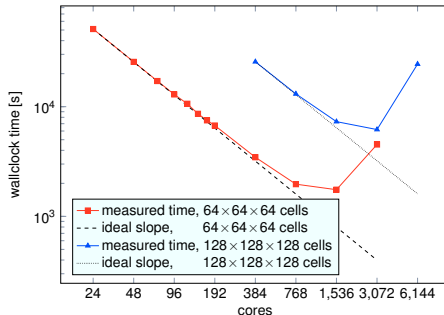
Initial mesh.

## Iterations of global refinement:

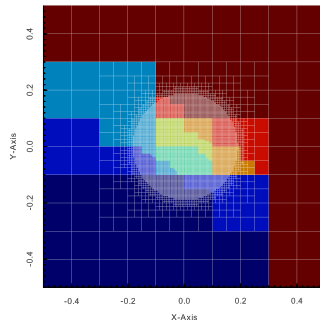


## HPC on JURECA: Parallelization

- MPI parallelization with Trilinos and p4est through deal.II backends



**Figure:** Strong scaling on JURECA for fixed 3D problems with 262,144 and 2,097,152 cells, respectively.



**Figure:** Exemplary domain decomposition with p4est in an AMR case.

# Summary & Outlook

## Summary:

- Adaptive Mesh Refinement works satisfactorily (for now)
- Flow solver accomplishes first verification tests

## Future work:

- Implementation of models
  - Radiation, combustion, pyrolysis, ...
- Extension of numerical methods
  - DG methods, p-adaptivity, ...
- Comparison with other fire solvers
- Validation using experiments

Thank you for your kind attention!

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*SIAM Undergraduate Research Online (SIURO)*, 7.



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[cited 04/02/2018].



# Fire Simulation with adaptive FEM: Addendum

April 3, 2018 | Marc Fehling | Civil Safety Research (CSR)

# FEM: Formulation

- Solve variational equation from 'weak' formulation of the differential equation with bilinear form  $a(u, v)$ :

$$\exists u \in V : \forall v \in V : a(u, v) = f(v)$$

- Choose subspace  $V_h$  with basis  $w_i$ , out of which the approximate solution  $u_h = \sum u_i w_i \in V_h$  will be constructed:

$$a(u_h, w_j) = \sum a(w_i, w_j) u_i = f(w_j) \rightarrow AU = F$$

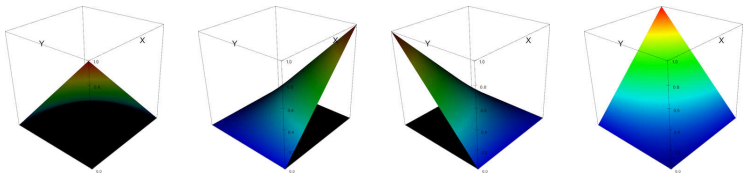


Figure:  $Q_1$  elements in 2D (source: deal.II)

## Our Implementation: Algorithm

- Time evolution with backward differentiation formula (BDF)
- Taylor–Hood elements [3]:  $(\mathbf{u}, p) \in Q_{k+1}^{\text{dim}} \times Q_k$
- Decoupling of  $(\mathbf{u}, p)$  by projection scheme
  - Leads to the pressure–Poisson equation
- Stabilization of momentum equation
  - Taylor–Galerkin stabilization [4] for Taylor–Hood elements
    - Additional diffusion in flow direction
  - Grad–div stabilization [5] to enforce  $\nabla \cdot \mathbf{u} = 0$
- Neumann series for fast matrix assembly
- Boussinesq approximation for buoyancy force density

## Verification: Richardson Extrapolation

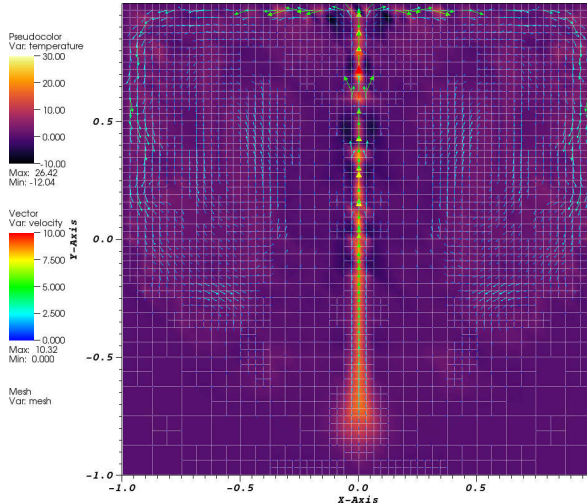
- How to get convergence rates of time **and** space dependent problems?
- Cancel out redundant error with Richardson extrapolation. Constant ratio  $r$  for successive refinement (here: space).

$$\left. \begin{aligned} f_1 - f_0 &= c_t \Delta t^{p_t} + c_h \Delta h^{p_h} \\ f_2 - f_0 &= c_t \Delta t^{p_t} + c_h (r \Delta h)^{p_h} \\ f_3 - f_0 &= c_t \Delta t^{p_t} + c_h (r^2 \Delta h)^{p_h} \end{aligned} \right\} \ln \left( \frac{f_3 - f_2}{f_2 - f_1} \right) = p_h \ln(r)$$

|        | Space  | Time   |
|--------|--------|--------|
| FDS    | 1.9244 | 2.0721 |
| JuFire | 3.0894 | 0.9715 |

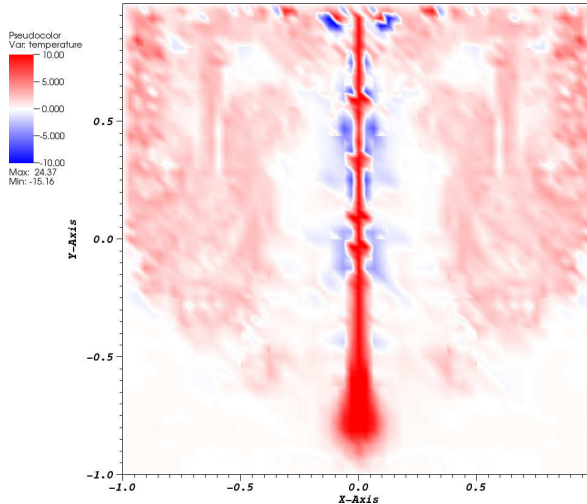
**Table:** Exemplary convergence rates for a McDermott testcase [6].

# Buoyancy driven flows – Work in progress



**Figure:** Video of velocity & temperature with constant heat source.

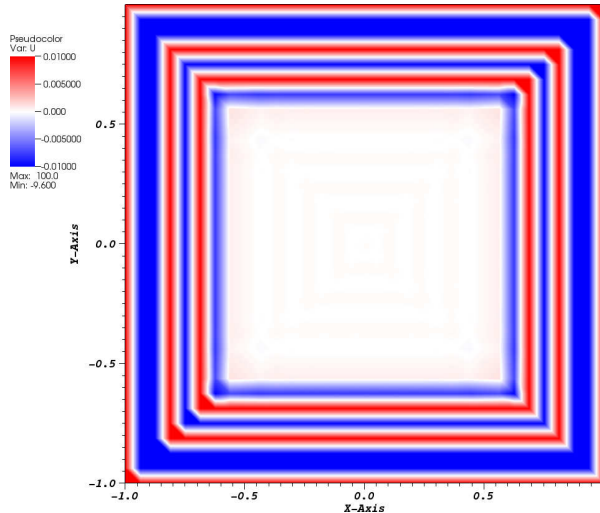
# Buoyancy driven flows – Possible error source



**Figure:** Temperature with constant heat source.

# Heat equation with FEM – Possible error source

$$\partial_t u - \nu \nabla^2 u = 0$$



**Figure:** Solution of heat equation at advanced time.