

Signal denoising through topographic modularity

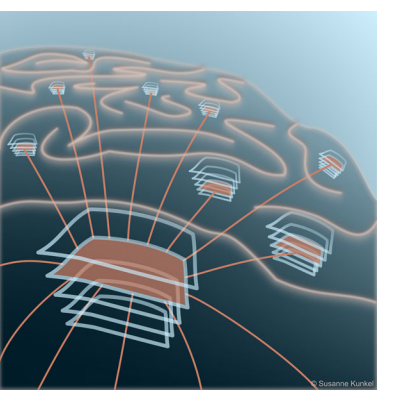
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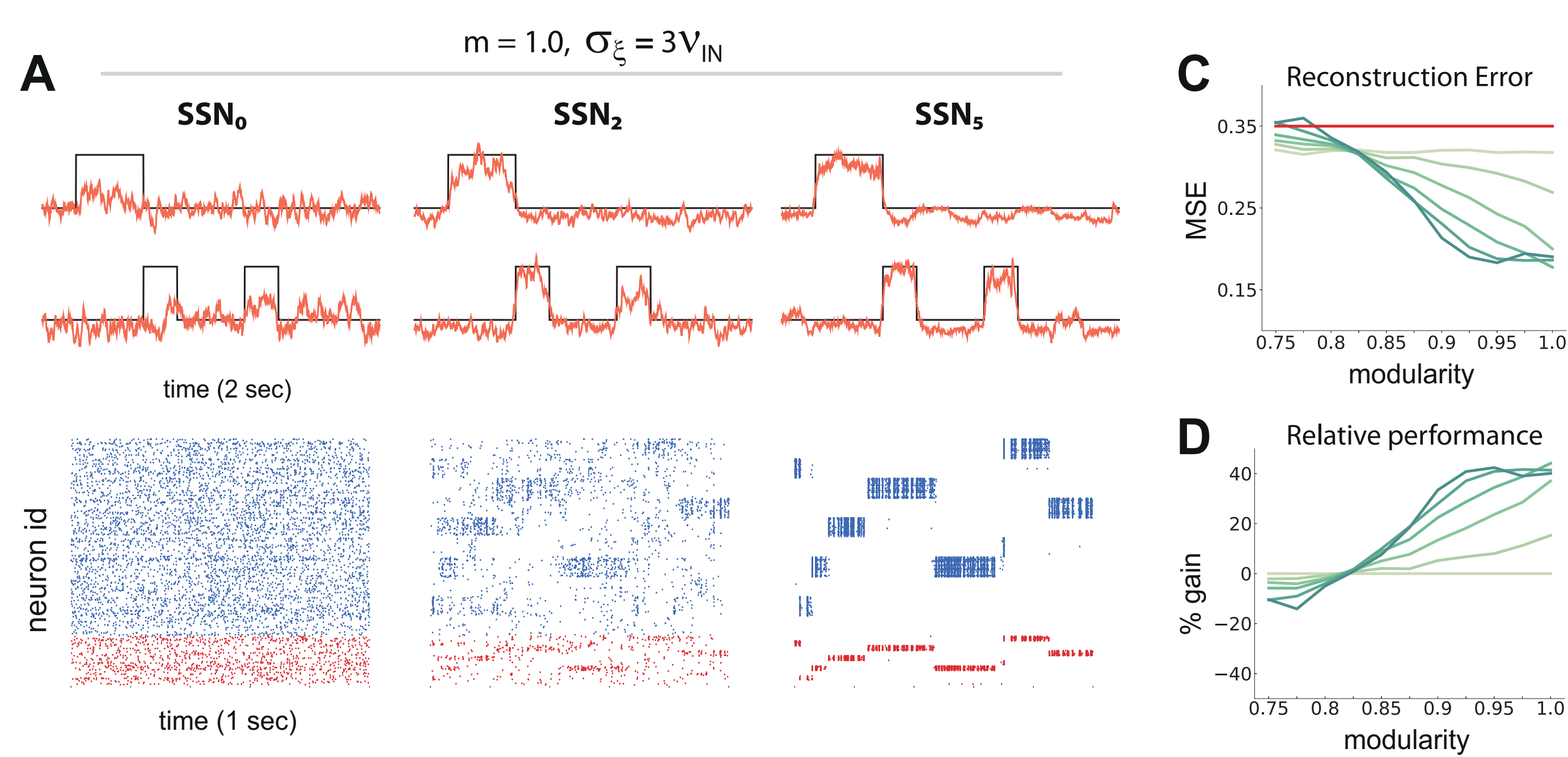
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1. Introduction

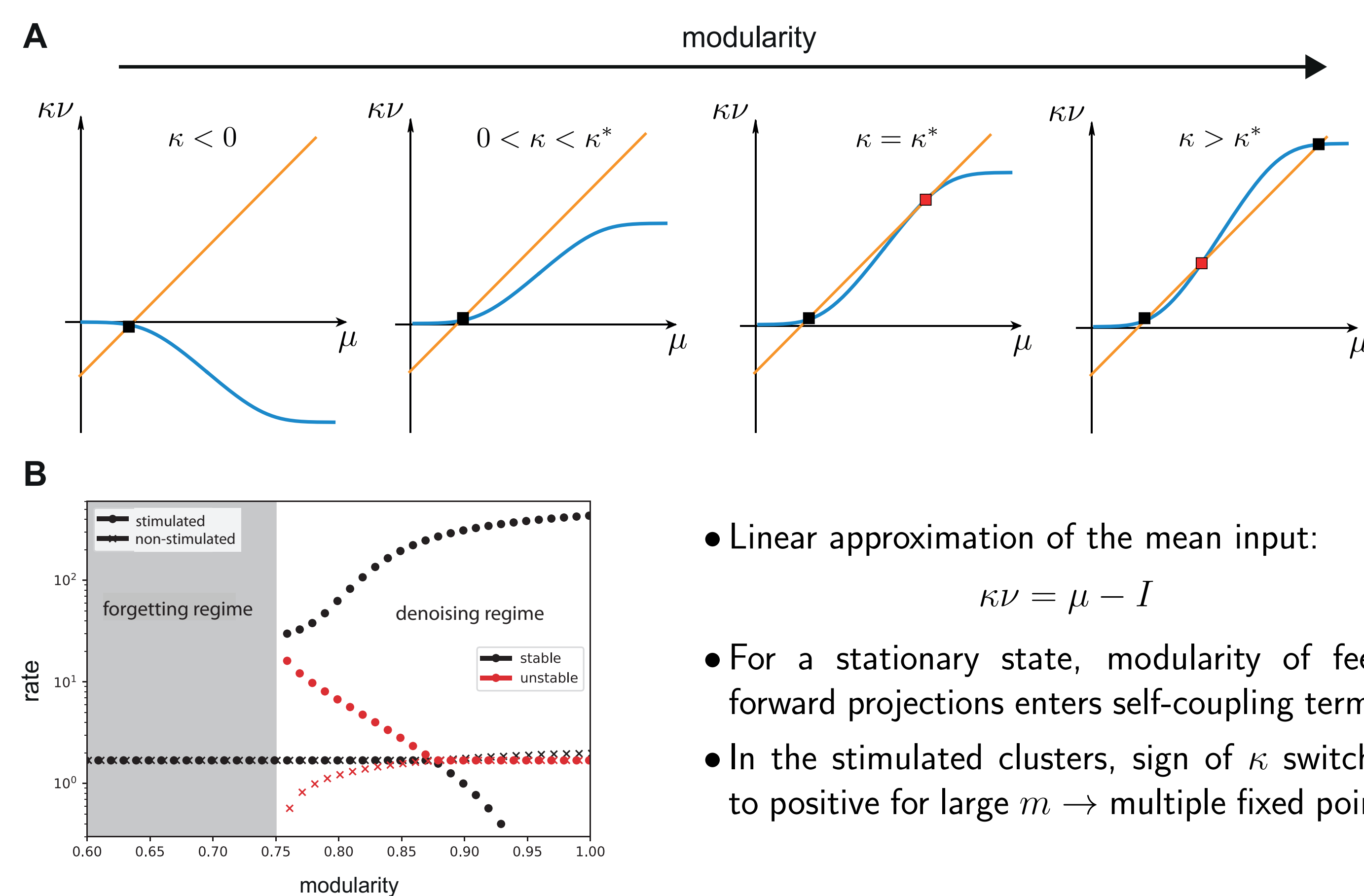
- Sensory inputs arriving at the cortical circuitry are often ambiguous, noisy and imprecise
- These are typically mapped onto tuned populations and processed through a series of topographic maps [3], comprising ordered projections among distinct neuronal populations
- Accurate sensory perception requires that external stimuli are encoded and propagated through different processing stages in a manner that minimizes signal degradation
- Here we hypothesize that stimulus-specific pathways akin to cortical topographic maps may provide the structural scaffold for such signal routing
 - Model: large modular circuit of spiking neurons comprising multiple sub-networks
 - Modular topographic precision can instantiate a effective denoising auto-encoder
 - Stimulus representation improves with network depth
 - Theory predicts that denoising may be a universal, system-agnostic feature of such maps

3. A de-facto denoising auto-encoder

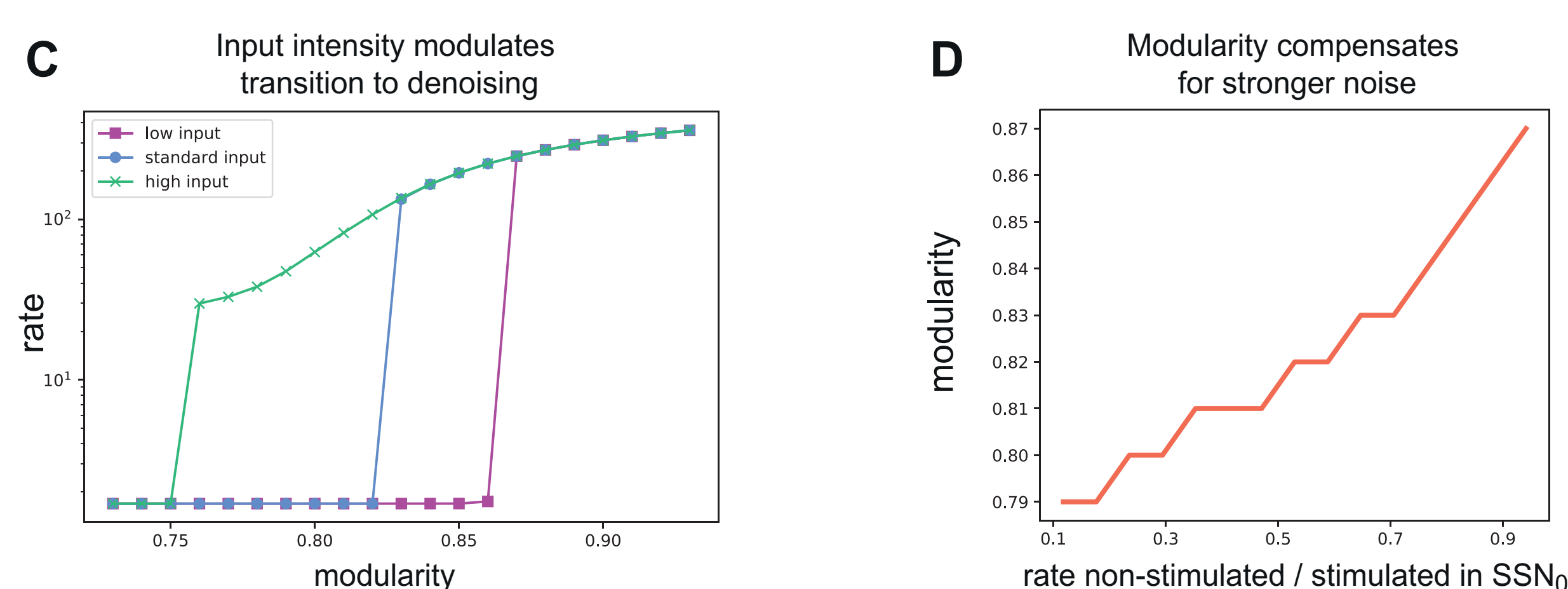


- Structured projections are essential for accurate signal reconstruction (see also [1])
- Beyond $m \approx 0.83$, the system behaves as an effective denoising auto-encoder
 - performance improves with network depth
- Modularity gradually sharpens population responses and encoding through spatial segregation
 - this results in both *noise suppression* and *response amplification*

5. Fixed point analysis



- Denoising effect: successively drive the rates of the stimulated (non-stimulated) clusters to the stable high-activity (low-activity, near zero) fixed point
- Switching point (m) is determined by stimulus intensity and input noise in SSN₀

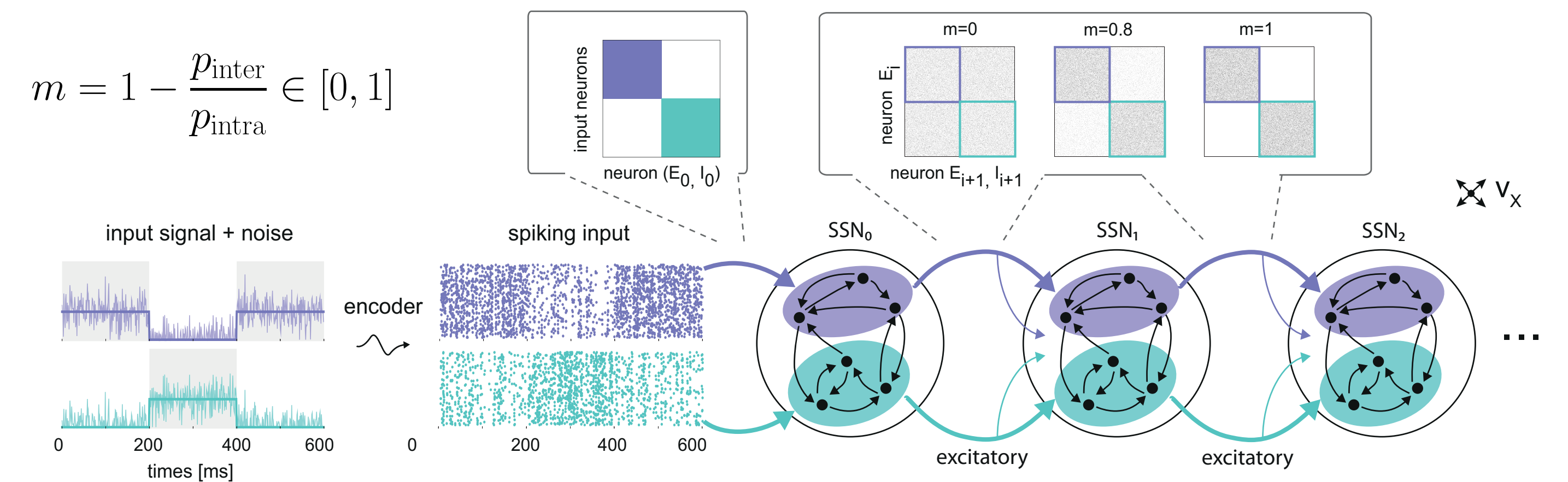


References

- [1] Zajzon, B. et al (2019). Passing the message: representation transfer in modular balanced networks. Frontiers in computational neuroscience, 13, 79. [2] Maass, W. et al (2002). Real-time computing without stable states: A new framework for neural computation based on perturbations. Neural computation, 14(11), 2531-2560. [3] Bednar, J. A., & Wilson, S. P. (2016). Cortical maps. The Neuroscientist, 22(6), 604-617.

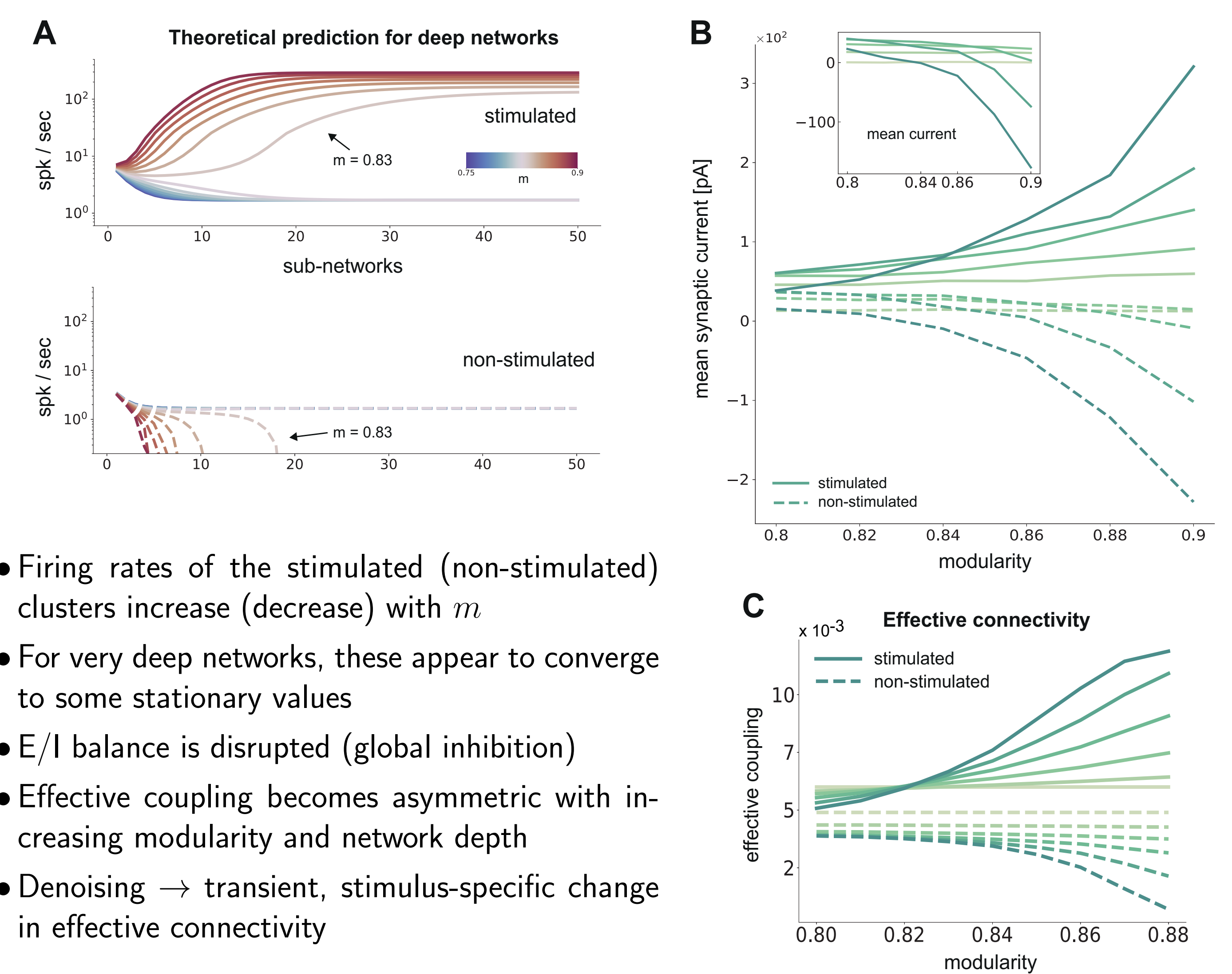
Acknowledgments: The authors gratefully acknowledge the computing time granted by the JARA Vergabegremium and provided on the JARA Partition part of the supercomputer JURECA at Forschungszentrum Jülich and the technical support of the Simulation Lab Neuroscience.

2. Network architecture & task



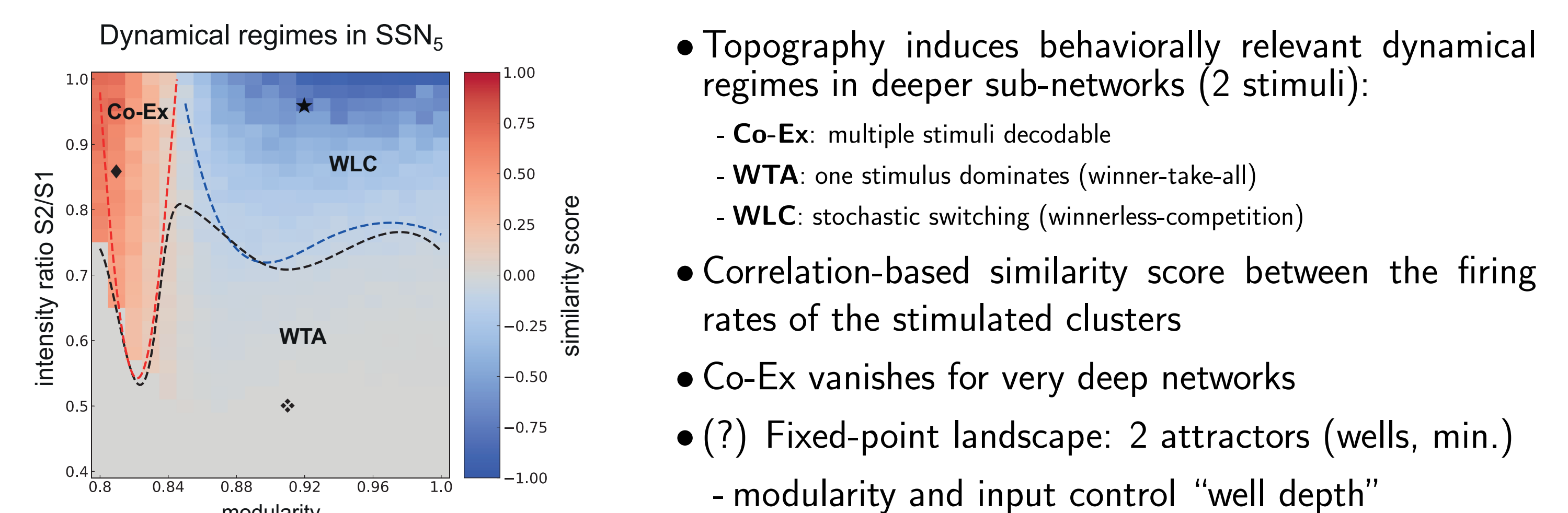
- Sequentially connected balanced random networks of LIF neurons (6 sub-networks, SSNs)
- Structured stimuli drive specific neuronal clusters in SSN₀, building a topographic map
- Task: reconstruct continuous signal corrupted by Gaussian noise, using Reservoir Computing [2]

4. Asymmetric coupling and E/I balance



- Firing rates of the stimulated (non-stimulated) clusters increase (decrease) with m
- For very deep networks, these appear to converge to some stationary values
- E/I balance is disrupted (global inhibition)
- Effective coupling becomes asymmetric with increasing modularity and network depth
- Denoising → transient, stimulus-specific change in effective connectivity

6. Multiple dynamical regimes



- Topography induces behaviorally relevant dynamical regimes in deeper sub-networks (2 stimuli):
 - Co-Ex: multiple stimuli decodable
 - WTA: one stimulus dominates (winner-take-all)
 - WLC: stochastic switching (winnerless-competition)
- Correlation-based similarity score between the firing rates of the stimulated clusters
- Co-Ex vanishes for very deep networks
- (?) Fixed-point landscape: 2 attractors (wells, min.)
 - modularity and input control “well depth”

Discussion

- We show, in biologically plausible setting, that the experimentally observed topographic maps may serve as a structural denoising mechanism for sensory stimuli
- Modularity changes the fixed point landscape, leading to bistable operating regimes
- Robust, general structural property (also for conductance-based synapses and rate networks)
- May explain multiple phenomena: pop-out effect, perceptual bistability
- ? Impact of different architectures: a) feedback projections; b) shared inhibition?
- ? Relation to other modular networks, e.g., clustered sub-populations within a local network?